Lecture 11: Magnetic Anisotropies

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In this lecture, we see ...

• It is not only O(n) models that we can study by considering the multiple-component field. We can deal with anisotropies as well.

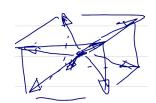
[11-1] Cubic anisotropy

- Real magnetic systems can never be truely isotropic because spins are coupled with orbital degrees of freedom that are subject to the influence of the lattice.
- In the case of the cubic lattice, for example, the localized spins feel the anisotropy field that has the same symmetry as the cubic lattice.

$$v\left((S_{i}^{x})^{4}+(S_{i}^{y})^{4}+(S_{i}^{z})^{4}\right)$$

Decoupled Ising fixed point

- To understand why this term represents the effect of the cubic lattice, consider the case where $v \to \infty$. In this limit, the spin has to point to one of the corners of the unit cell (cube).
- Note that in this limit, the system becomes 3 decoupled Ising models. We will find a fixed point corresponding to this limit.



Scaling operators

- For the ε-expansion of the systems with the cubic symmetry, we consider [···] of each term in the Hamiltonian.
- *t*-operator:

$$\phi_t \equiv \sum_{\alpha} \llbracket \phi^{\alpha}(\mathbf{x}) \phi^{\alpha}(\mathbf{x}) \rrbracket$$

• *u*-operator:

$$\phi_u \equiv \sum_{\alpha\beta} \left[\phi^{\alpha}(\mathbf{x}) \phi^{\alpha}(\mathbf{x}) \phi^{\beta}(\mathbf{x}) \phi^{\beta}(\mathbf{x}) \right]$$

v-operator:

$$\phi_{\mathbf{v}} \equiv \sum_{\alpha} \llbracket \phi^{\alpha}(\mathbf{x}) \phi^{\alpha}(\mathbf{x}) \phi^{\alpha}(\mathbf{x}) \phi^{\alpha}(\mathbf{x}) \rrbracket$$



OPE

•
$$\phi_t \phi_u \approx \cdots + 8\phi_u + 4(n+2)\phi_t + \cdots$$

$$c_{tu}^{t} = 4(n+2), \quad c_{tu}^{u} = 8, \quad c_{tu}^{v} = 0$$

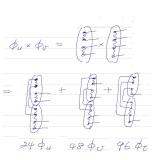
• $\phi_t \phi_v \approx \cdots + 8\phi_v + 12\phi_t + \cdots$

$$c_{tv}^{t} = 12, \quad c_{tv}^{u} = 0, \quad c_{tv}^{v} = 8$$

$$c_{uv}^t = 96, \quad c_{uv}^u = 24, \quad c_{uv}^v = 48$$

• $\phi_{\mathbf{v}}\phi_{\mathbf{v}}\approx\cdots+72\phi_{\mathbf{v}}+96\phi_{t}+\cdots$

$$c_{vv}^{t} = 96, \quad c_{vv}^{u} = 0, \quad c_{vv}^{v} = 72$$



RG flow equation

• Keeping in mind that $u = O(\epsilon)$ and $t = O(\epsilon^2)$, as before, the part of the RG flow equation necessary for the lowest order discussion is

$$\begin{cases} \frac{dt}{d\lambda} = A \equiv 2t - 8(n+2)tu - 24tv + \cdots \\ \frac{du}{d\lambda} = B \equiv \epsilon u - 8(n+8)u^2 - 48uv + \cdots \\ \frac{dv}{d\lambda} = C \equiv \epsilon v - 96uv - 72v^2 + \cdots \end{cases}$$

Note that we have omitted the terms, such as tu in B and u^2 in A, that would not contribute to y_t, y_u, y_v at the non-Gaussian FPs.

- We have four fixed points:
 - **1** [G] (t, u, v) = (0, 0, 0)
 - ② [WF] $(t, u, v) = (t_{WF}^*, u_{WF}^*, 0)$
 - **3** [DI] $(t, u, v) = (t_{DI}^*, 0, v_{DI}^*)$ ("decoupled Ising FP")
 - **1** [C] $(t, u, v) = (t_C^*, u_C^*, v_C^*)$ ("cubic FP")

Linearization

• In all cases, we have the same form of the linearized RG flow eqs. in terms of $\Delta \mathbf{u} \equiv (t - t^*, u - u^*, v - v^*)^{\mathsf{T}}$:

$$\frac{d\Delta \mathbf{u}}{d\lambda} = Y\Delta \mathbf{u}$$

where
$$Y \equiv \begin{pmatrix} \frac{\partial A}{\partial t} & \frac{\partial A}{\partial u} & \frac{\partial A}{\partial v} \\ \frac{\partial B}{\partial t} & \frac{\partial B}{\partial u} & \frac{\partial B}{\partial v} \\ \frac{\partial C}{\partial t} & \frac{\partial C}{\partial u} & \frac{\partial C}{\partial v} \end{pmatrix}_{t^*,u^*,v^*}$$

$$\equiv \begin{pmatrix} 2 - 8(n+2)u^* - 24v^* & O(\epsilon) & O(\epsilon) \\ O(\epsilon) & \epsilon - 16(n+8)u^* - 48v^* & -48u^* \\ O(\epsilon) & -96v^* & \epsilon - 96u^* - 144v^* \end{pmatrix}$$

• The lower-right 2×2 sub-matrix is important:

$$\frac{\partial(B,C)}{\partial(u,v)} = \begin{pmatrix} \epsilon - 16(n+8)u^* - 48v^* & -48u^* \\ -96v^* & \epsilon - 96u^* - 144v^* \end{pmatrix}$$

"WF" \cdots O(n) Wilson-Fisher FP

• Within the manifold of v = 0, obviously, all results will be the same as before:

$$t_{\text{WF}}^* = \frac{\epsilon^2}{4(n+8)^2}$$
 and $u_{\text{WF}}^* = \frac{\epsilon}{8(n+8)}$.

• The (u, v)-part of the Y matrix becomes

$$\frac{\partial(B,C)}{\partial(u,v)} = \epsilon \times \begin{pmatrix} -1 & -\frac{6}{n+8} \\ 0 & \frac{n-4}{n+8} \end{pmatrix}$$

• The eigenvalues and eigenvectors are

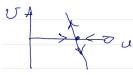
$$y_u^{\mathsf{WF}} \equiv -\epsilon \cdots \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad y_v^{\mathsf{WF}} = \frac{n-4}{n+8}\epsilon \cdots \begin{pmatrix} -1 \\ \frac{n+2}{3} \end{pmatrix}$$

• Therefore, we have $n_c \approx 4$ and the WFFP is stable if $n < n_c$.

Case 1: $n < n_c$



Case 2:
$$n > n_c$$



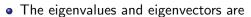
"DI" · · · Decoupled Ising fixed point

• Remembering the RG flow equation for v, we find a FP with $u^* = 0$:

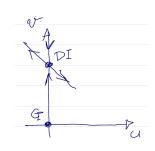
$$(u_{\mathsf{DI}}^*, v_{\mathsf{DI}}^*) = \left(0, \frac{\epsilon}{72}\right).$$

• The (u, v)-part of the Y matrix becomes

$$\frac{\partial(B,C)}{\partial(u,v)} = \begin{pmatrix} \epsilon - 48v^* & 0\\ -96v^* & \epsilon - 144v^* \end{pmatrix}$$
$$= \epsilon \cdot \begin{pmatrix} 1/3 & 0\\ -4/3 & -1 \end{pmatrix}$$



$$y_u^{\mathsf{DI}} \equiv \frac{\epsilon}{3} \cdots \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \quad y_t^{\mathsf{DI}} = -\epsilon \cdots \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$



10 / 1

"C" · · · Cubic fixed point

• Assuming $u, v = O(\epsilon)$ and $t = O(\epsilon^2)$,

$$(u_{\mathsf{C}}^*, v_{\mathsf{C}}^*) = \left(\frac{\epsilon}{24n}, \frac{(n-4)\epsilon}{72n}\right).$$

• The (u, v)-part of the Y matrix becomes

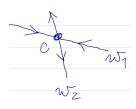
$$\frac{\partial(B,C)}{\partial(u,v)} = -\frac{\epsilon}{3n} \cdot \left(\begin{array}{cc} n+8 & 6 \\ 4(n-4) & 3(n-4) \end{array} \right)$$

The eigenvalues and eigenvectors are

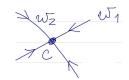
$$y_{w_1}^{\mathsf{C}} = -\epsilon \quad \cdots \begin{pmatrix} 3 \\ n-4 \end{pmatrix},$$

$$y_{w_2}^{\mathsf{C}} = -\frac{n-4}{3n}\epsilon \quad \cdots \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

Case 1: $n < n_c$



Case 2: $n > n_c$



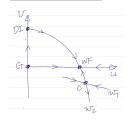
Global structure of RG flow

 Putting together, we can draw the RG flow diagram including the 4 fixed points.

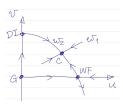
	$n < n_c$ $u^* > 0, v^* < 0$	$n > n_c$ $u^* > 0, v^* > 0$
G	$y_u > 0, y_v > 0$	$y_u > 0, y_v > 0$
WF	$y_u < 0, y_v < 0$	$y_u < 0, y_v > 0$
DI	$y_u > 0, y_v < 0$	$y_u > 0, y_v < 0$
С	$y_{w_1} < 0, y_{w_1} > 0$	$y_{w_2} < 0, y_{w_2} < 0$

- Depending on whether $n < n_c$ or $n > n_c$ we can draw two types of the diagram.
- So, after all the cubic anisotropy is irrelevant for real magnetic systems?

Case 1: $n < n_c$



Case 2: $n > n_c$



Nature of the transition in real magnets

- The value for n_c seems to be close to 3 in 3D. So, there has been a long-standing controversy about the nature of the ferromagnetic transition under the cubic anisotropy.
- According to [Varnashev: PRB 61 14660 (2000)] $n_c(d=3) < 3$, or more specifically $n_c(d=3) = 2.89(2)$.
- For general discussion see [Calabrese et al: arXiv:cond-mat/0509415].

Summary

- By representing the cubic anisotropy by the term $v \sum_{\alpha} (\phi_i^{\alpha})^4$, we have constructed a field theory that may explain the effect of the lattice anisotropy on the spin systems that is otherwise symmetric.
- The ϵ -expansion of the ϕ^4 model with the v term produces a new fixed point. (Cubic fixed point)
- The cubic fixed point is stable for $n > n_c$ whereas it is unstable for $n < n_c$, where $n_c = 4 + O(\epsilon)$.
- According to a more sophisticated numerical estimate, n_c in 3D is slightly below 3, which suggests that we cannot simply neglect the cubic anisotropy in 3D.
- However, the critical region may be narrow in real systems due to smallness of the cubic anisotropy field and the proximity of n_c to 3.

Homework (submit your report at the next lecture)

 Consider the critical point of the Heisenberg model. Discuss the effect of the uniaxial symmetry breaking-field that is represented by adding the term

$$-D\left[(S_i^z)^2 - \frac{1}{2}((S_i^x)^2 + (S_i^y)^2)\right]$$

to the isotropic Hamiltonian, i.e., the regular Heisenberg model. (Consider the scaling dimension of the scaling operator that corresponds to the above operator, and obtain its scaling dimension at the Wilson-Fisher fixed point for n=3, to the lowest order in ϵ .)